



SNAP Supernova/Acceleration Probe

REU Summer Project 2003

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What is SNAP?

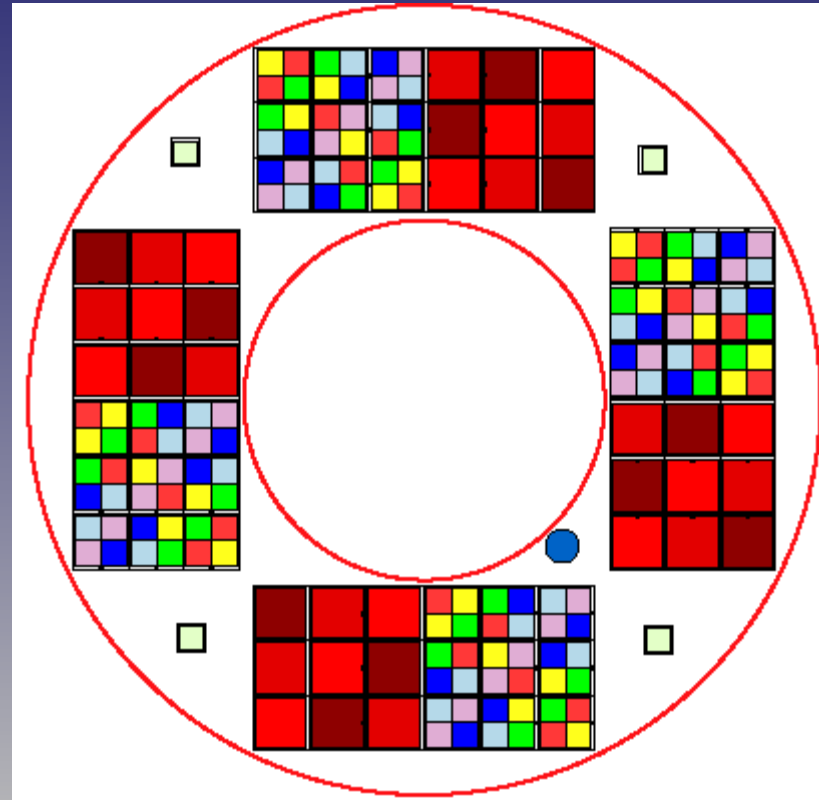
SNAP is a space-based telescope designed to measure the dark energy of the universe.

It will use 36 CCDs and 36 HgCdTe NIR detectors to survey the sky with detail never before achieved.

Will look at over 2000 type IA SNe from redshift $z=0.1$ to 1.7, using them as standard candles to measure both the amount and nature of the dark energy.

- **Spot-o-matic**
- **SNAP utilizes 36 HgCdTe NIR detectors, each with 4 million pixels**
- **To image the universe in the detail that SNAP seeks, each pixel on these detectors must be tested and characterized.**
- **Must shine a sub-pixel sized spot onto the detector, and be able to move it around VERY precisely**

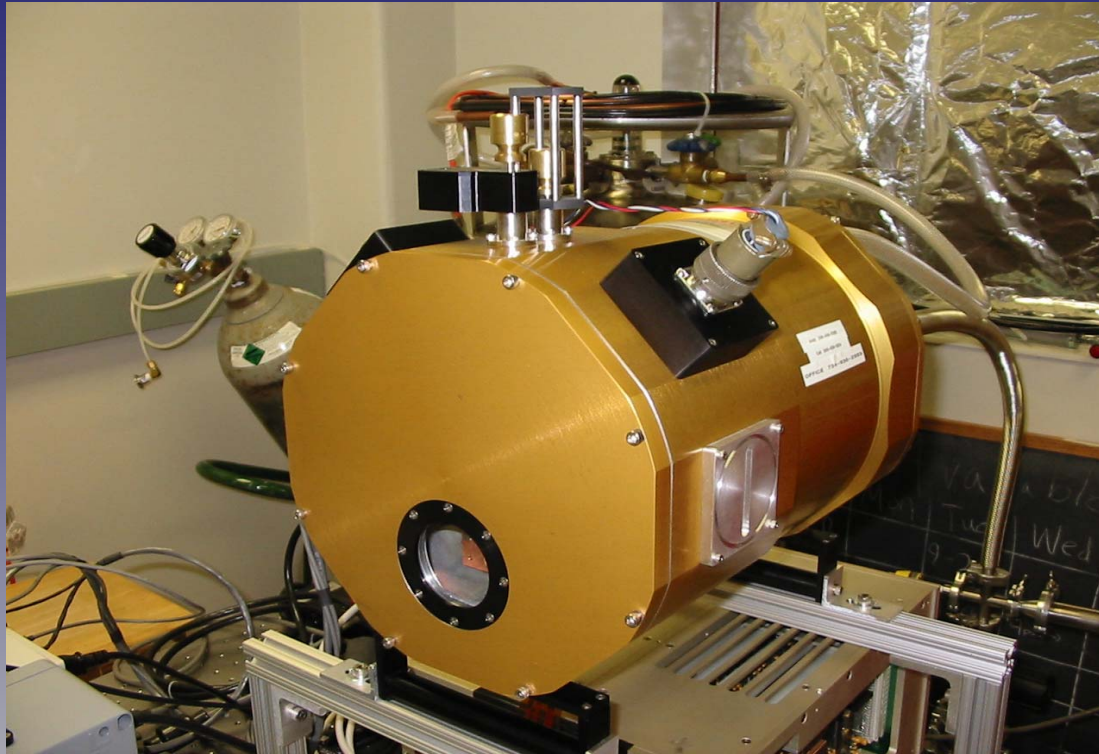
SNAP Detector Design



Each HgCdTe detector has 4 million pixels,
each of which must be tested!

Spot-o-matic

Detector Design



Detector to be tested is mounted inside a dewar to keep it at 140K.

Dewar necessitates a long working distance!

Spot-o-matic

Testing the detector

We need to test:

Lateral Charge Diffusion

Intrapixel variation in sensitivity

Pixel to Pixel uniformity

Absolute pixel size

How we test for all these

Pixels are approx 18micron across

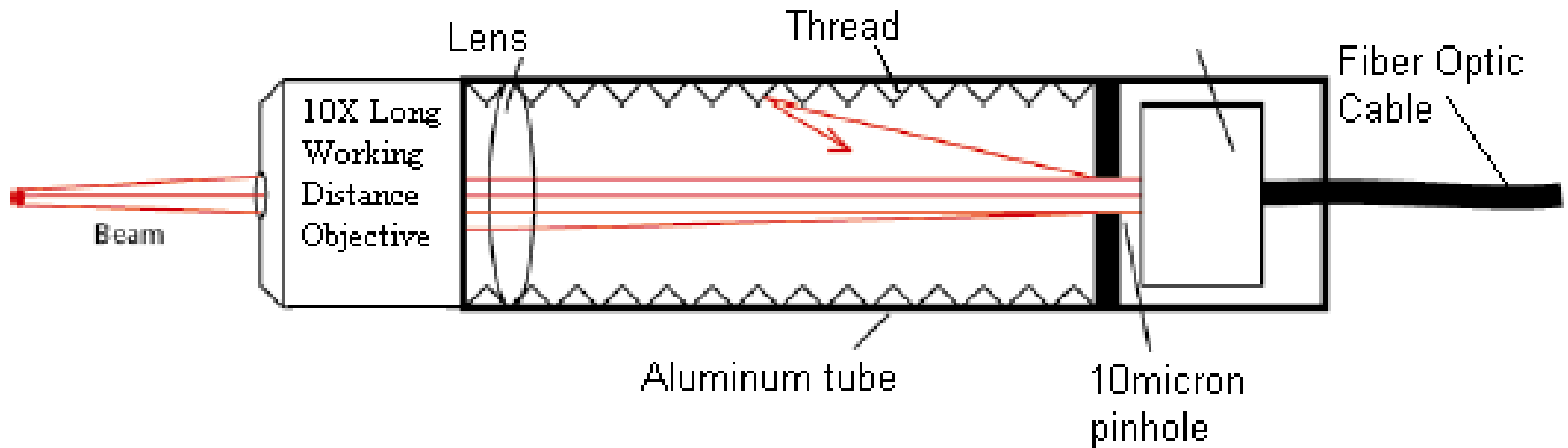
We need to focus a very small (approx 3micron diameter) uniform spot of light into the dewar and onto an individual pixel.

It needs to be small enough and with motion control accurate enough to move about inside a single pixel.

Spot-o-matic

How we did it

Idea borrowed from an LBL design, adapted for NIR light.



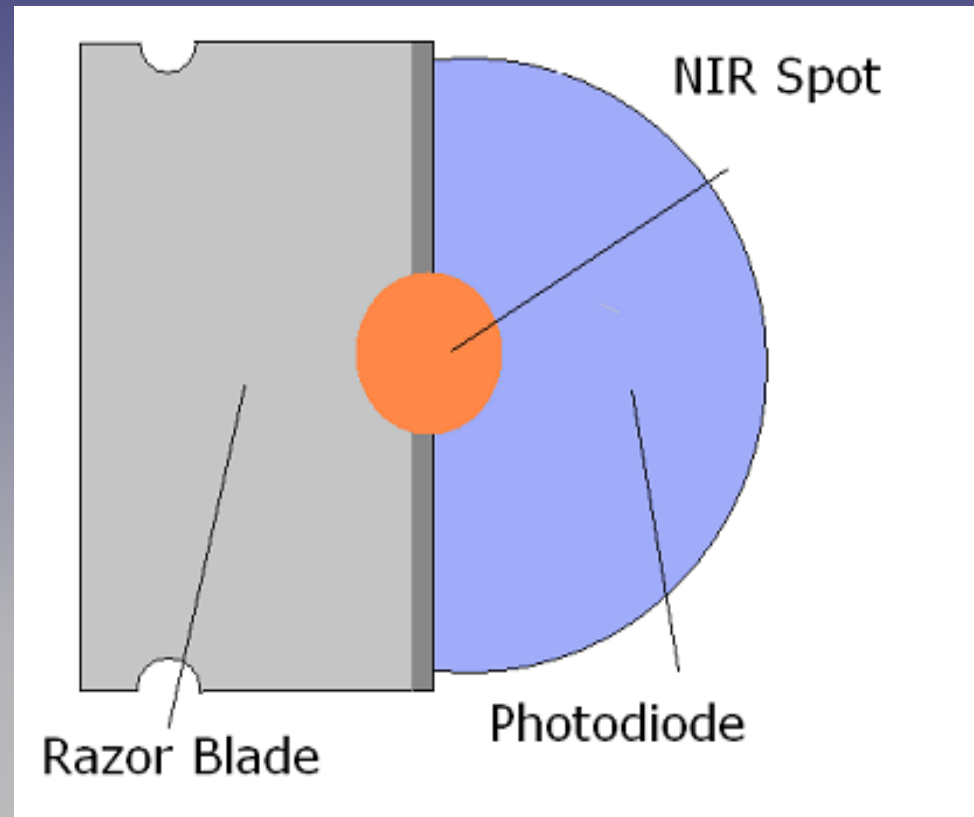
Courtesy of W. Kolbe, LBL 2002

Spot-o-matic

How do you actually measure how big the spot really is?

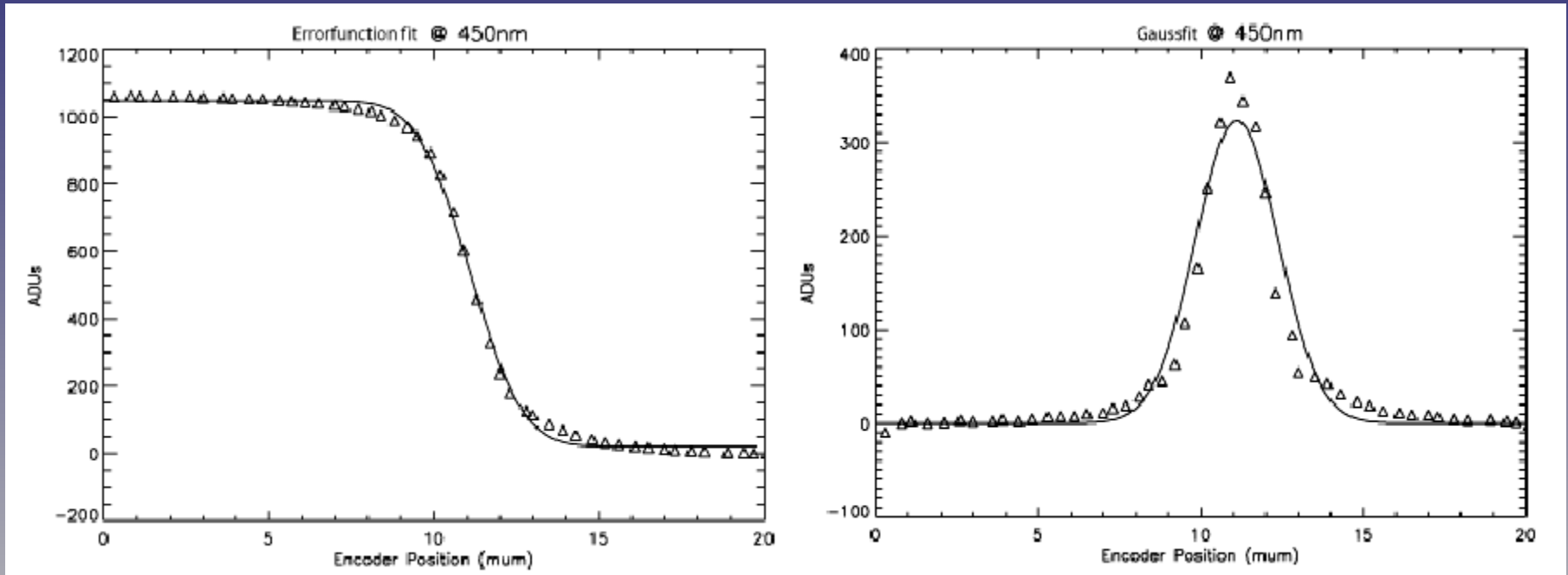
Use the knife-edge experiment to find the integral of intensity vs. distance.

Then take derivative to find the beam profile.



Spot-o-matic

Anticipated Results

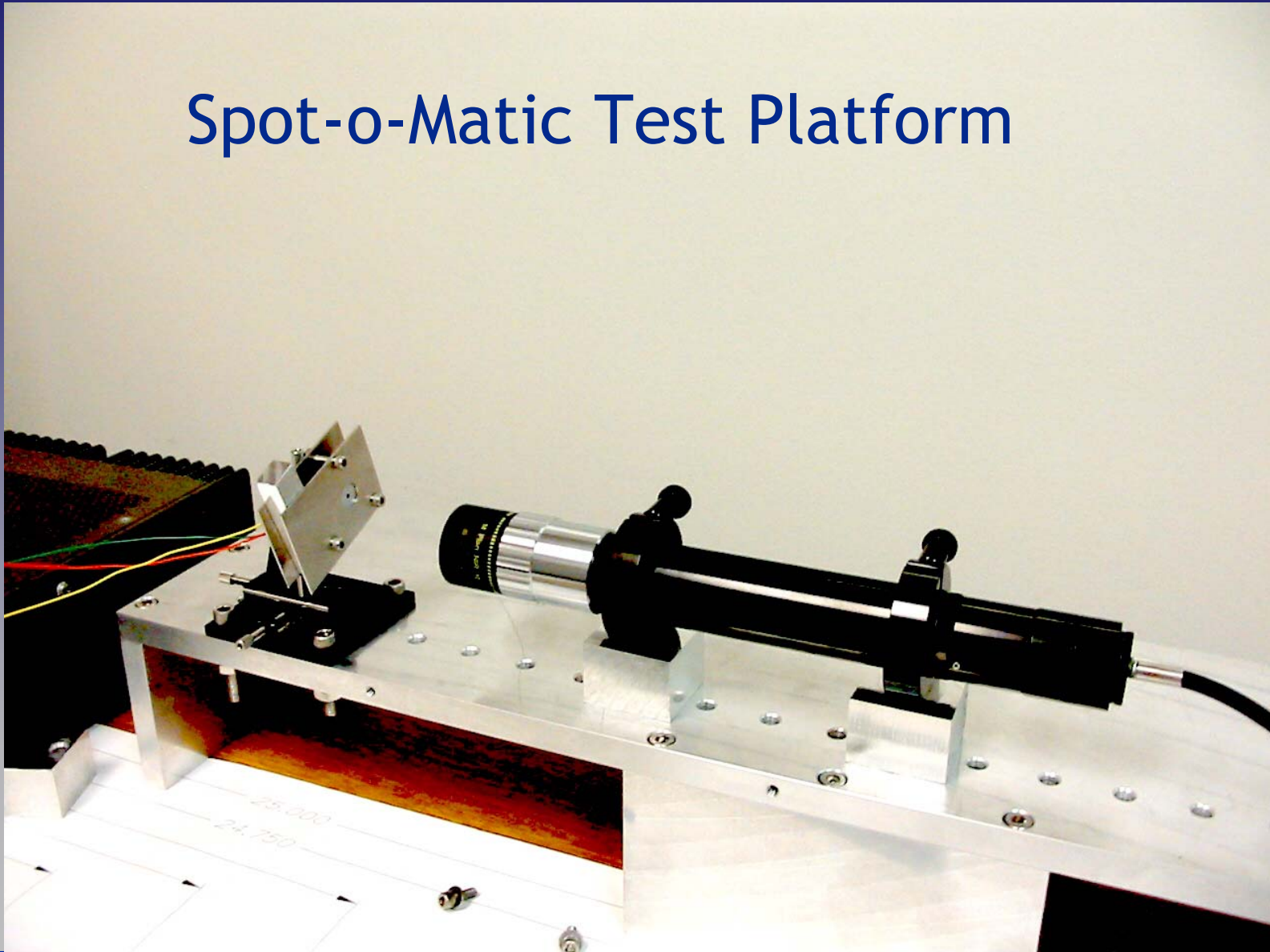


Results from LBL

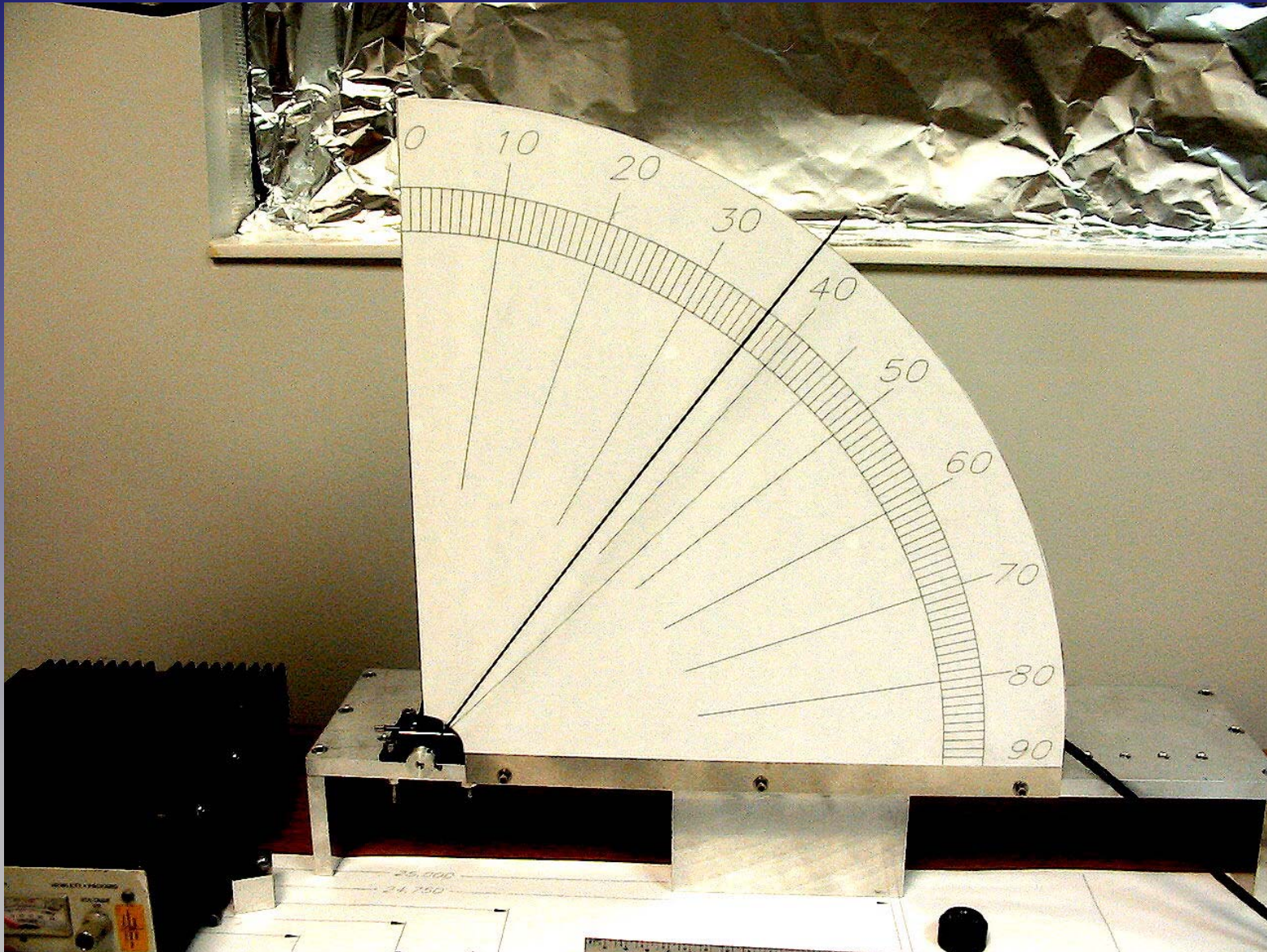
Our results should look much like this.

Spot-o-matic

Spot-o-Matic Test Platform



Spot-o-matic



Spot-o-matic

Current Progress

Setup is completely ready except for the tube lens that we are still waiting on.

Upon arrival of the lens, measurement of spot size can be conducted.

Once spot size is confirmed, the spot-o-matic will be mounted on a motorized stage, and characterization of the detector can begin. Hope to have results in November 2003.

Automation

The Spot-O-Matic will eventually be mounted on a motorized, computer controlled X-Y-Z stage.

Control of the motion will be completely integrated into the detector read-out software.