

Optimization Models for Differentiating Quality of Service Levels in Probabilistic Network Capacity Design Problems

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Introduction I

- Network design problems (NDPs) are essential for the development of modern societies
- Objective: Minimize flow cost and arc capacity modification cost



Figure : Internet cable network¹



Figure : Road network²

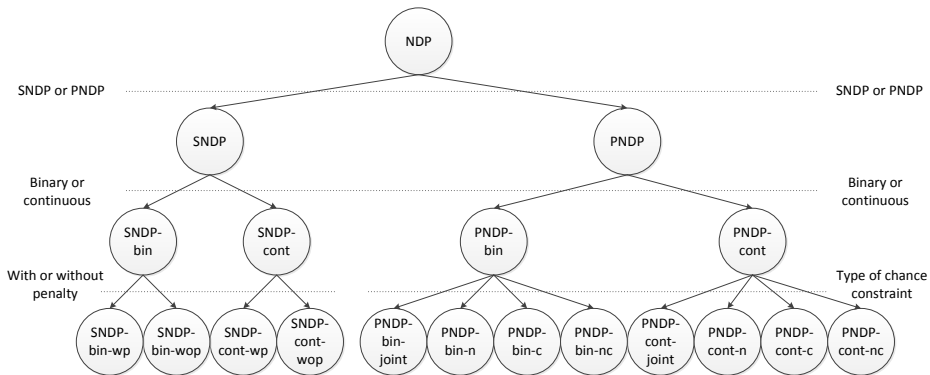
¹Source: <http://jamesdudleyonline.com/wp-content/uploads/2011/03/connect-through-the-internet.jpg>

²Source: <http://static.panoramio.com/photos/large/8248689.jpg>

Introduction II

- NPDs under demand uncertainty and with multiple commodities
- Capacity design decisions are made before realization of demands
 - Can be continuous or binary
- Probabilistic NDPs (**PNDPs**): Flow decisions made *before* realization of demands
 - Flow decisions are made under probabilistic constraints
 - Probabilistic constraints can be joint, or differentiated by node, commodity, or node and commodity
- Stochastic NDPs (**SNDPs**): Flow decisions made *after* realization of demands
 - *Expected* flow costs
 - Flow decisions may be penalized for unmet demand for greater flexibility in solution

Introduction III



Notation I

Graph: $G(N, A)$

Sets:

- W : Set of commodities
- $O_w \subseteq N$: Set of origins of commodity $w \in W$
- $D_w \subseteq N$: Set of destinations of commodity $w \in W$
- Ω : Set of random scenarios where $\Omega = \{1, \dots, |\Omega|\}$

Notation II

Parameters:

- c_{ij} : Cost of allocating one unit of capacity at link $(i, j) \in A$
- q_{ij} : Fixed cost of adding link $(i, j) \in A$ when capacity design variables are binary
- a_{ijw} : Unit cost of flowing commodity $w \in W$ on link $(i, j) \in A$
- u_{ij} : Fixed capacity of link $(i, j) \in A$ when capacity design variables are binary
- v_{iw} : Unit penalty cost of unmet demand of commodity w at destination $i \in D_w$
- o_{iw} : Deterministic supply of commodity w at origin $i \in O_w$
- d_{iw} : Random demand of commodity w at destination $i \in D_w$
- ξ_{iw}^s : Realization of random demand d_{iw} in scenario $s \in \Omega$, $\forall w \in W$ and $i \in D_w$
- p^s : Probability of scenario $s \in \Omega$
- $\epsilon, \epsilon_{iw}, \epsilon_i, \epsilon_w$: Risk parameters associated with different forms of chance constraints

PNDP formulations I

PNDP-cont-joint:

$$\begin{aligned} \min_{\mathbf{x}, \mathbf{y}} \quad & \sum_{(i,j) \in A} c_{ij} x_{ij} + \sum_{w \in W} \sum_{(i,j) \in A} a_{ijw} y_{ijw} \\ \text{s.t.} \quad & \sum_{w \in W} y_{ijw} \leq x_{ij} \quad \forall (i,j) \in A \end{aligned} \quad (1)$$

$$\sum_{j:(i,j) \in A} y_{ijw} - \sum_{j:(j,i) \in A} y_{jiw} \leq o_{iw} \quad \forall i \in O_w, w \in W \quad (2)$$

$$\sum_{j:(i,j) \in A} y_{ijw} - \sum_{j:(j,i) \in A} y_{jiw} = 0 \quad \forall i \notin O_w \cup D_w, w \in W \quad (3)$$

$$\mathbf{x} \geq 0, \mathbf{y} \geq 0 \quad (4)$$

$$\mathbb{P} \left(\sum_{j:(j,i) \in A} y_{jiw} - \sum_{j:(i,j) \in A} y_{ijw} \geq d_{iw}, \forall i \in D_w, w \in W \right) \geq 1 - \epsilon$$

PNDP formulations II

PNDP-cont-n:

$$\min_{\mathbf{x}, \mathbf{y}} \quad \sum_{(i,j) \in A} c_{ij} x_{ij} + \sum_{w \in W} \sum_{(i,j) \in A} a_{ijw} y_{ijw}$$

$$\text{s.t.} \quad (1)-(4)$$

$$\mathbb{P} \left(\sum_{j:(j,i) \in A} y_{jiw} - \sum_{j:(i,j) \in A} y_{ijw} \geq d_{iw}, \forall w \in W \right) \geq 1 - \epsilon_i, \quad \forall i \in \bigcup_{w \in W} D_w$$

PNDP-cont-c:

$$\min_{\mathbf{x}, \mathbf{y}} \quad \sum_{(i,j) \in A} c_{ij} x_{ij} + \sum_{w \in W} \sum_{(i,j) \in A} a_{ijw} y_{ijw}$$

$$\text{s.t.} \quad (1)-(4)$$

$$\mathbb{P} \left(\sum_{j:(j,i) \in A} y_{jiw} - \sum_{j:(i,j) \in A} y_{ijw} \geq d_{iw}, \forall i \in D_w \right) \geq 1 - \epsilon_w, \quad \forall w \in W$$

PNDP formulations III

PNDP-cont-nc:

$$\min_{\mathbf{x}, \mathbf{y}} \sum_{(i,j) \in A} c_{ij} x_{ij} + \sum_{w \in W} \sum_{(i,j) \in A} a_{ijw} y_{ijw}$$

s.t. (2);(3)

$$\sum_{w \in W} y_{ijw} \leq x_{ij} \quad \forall (i,j) \in A$$

$$\mathbf{x} \geq 0, \mathbf{y} \geq 0$$

$$\mathbb{P} \left(\sum_{j:(j,i) \in A} y_{j iw} - \sum_{j:(i,j) \in A} y_{ijw} \geq d_{iw} \right) \geq 1 - \epsilon_{iw}, \quad \forall i \in D_w, w \in W$$

PNDP formulations IV

PNDP-bin-nc:

$$\min_{\beta, \mathbf{y}} \sum_{(i,j) \in A} q_{ij} \beta_{ij} + \sum_{w \in W} \sum_{(i,j) \in A} a_{ijw} y_{ijw}$$

s.t. (2);(3)

$$\sum_{w \in W} y_{ijw} \leq u_{ij} \beta_{ij} \quad \forall (i, j) \in A$$

$$\beta \in \{0, 1\}^{|A|}, \mathbf{y} \geq 0$$

$$\mathbb{P} \left(\sum_{j:(j,i) \in A} y_{j iw} - \sum_{j:(i,j) \in A} y_{ijw} \geq d_{iw} \right) \geq 1 - \epsilon_{iw}, \quad \forall i \in D_w, w \in W$$

SNDP formulations I

SNDP-cont-wop:

$$\min_{\mathbf{x}, \mathbf{y}} \sum_{(i,j) \in A} c_{ij} x_{ij} + \sum_{s \in \Omega} p^s \left(\sum_{w \in W} \sum_{(i,j) \in A} a_{ijw} y_{ijw}^s \right)$$

$$\text{s.t.} \quad \sum_{w \in W} y_{ijw}^s \leq x_{ij} \quad \forall (i,j) \in A, s \in \Omega \quad (5)$$

$$\sum_{j:(i,j) \in A} y_{ijw}^s - \sum_{j:(j,i) \in A} y_{jiw}^s \leq o_{iw} \quad \forall i \in O_w, w \in W, s \in \Omega \quad (6)$$

$$\sum_{j:(i,j) \in A} y_{ijw}^s - \sum_{j:(j,i) \in A} y_{jiw}^s = 0 \quad \forall i \notin O_w \cup D_w, w \in W, s \in \Omega \quad (7)$$

$$\mathbf{x} \geq 0, \mathbf{y}^s \geq 0 \quad \forall s \in \Omega \quad (8)$$

$$- \sum_{j:(i,j) \in A} y_{ijw}^s + \sum_{j:(j,i) \in A} y_{jiw}^s \geq \xi_{iw}^s \quad \forall i \in D_w, w \in W, s \in \Omega$$

SNDP formulations II

SNDP-cont-wp:

$$\begin{aligned} \min_{\mathbf{x}, \mathbf{y}} \quad & \sum_{(i,j) \in A} c_{ij} x_{ij} + \sum_{s \in \Omega} p^s \left(\sum_{w \in W} \sum_{(i,j) \in A} a_{ijw} y_{ijw}^s + \sum_{w \in W} \sum_{i \in D_w} v_{iw} t_{iw}^s \right) \\ \text{s.t.} \quad & (5)-(8) \\ & - \sum_{j:(i,j) \in A} y_{ijw}^s + \sum_{j:(j,i) \in A} y_{jiw}^s + t_{iw}^s \geq \xi_{iw}^s \quad \forall i \in D_w, w \in W, s \in \Omega \\ & \mathbf{t}^s \geq 0 \quad \forall s \in \Omega \end{aligned}$$

-
- SNDPs can be solved as a two-stage problem using Benders' decomposition
 - SNDP-cont-wp is typically used to formulate cost-based NDPs
 - A benchmark against which we compare our PNDP-cont reformulations

Big-M reformulation of chance constraints I

Approach:

- Add binary variable z^s that takes value 1 if the chance constraint is violated by demand realization ξ^s and 0 otherwise
- The sum of probabilities of the realizations that violate the chance constraint must not exceed the tolerance level

Big-M reformulation of chance constraints II

Example: **PNDP-cont-nc**

$$\mathbb{P} \left(\sum_{j:(j,i) \in A} y_{jiw} - \sum_{j:(i,j) \in A} y_{ijw} \geq d_{iw} \right) \geq 1 - \epsilon_{iw}, \quad \forall i \in D_w, w \in W$$

Create a new variable z_{iw}^s such that

$$z_{iw}^s = \begin{cases} 1 & \text{if } \sum_{j:(j,i) \in A} y_{jiw} - \sum_{j:(i,j) \in A} y_{ijw} < \xi_{iw}^s \\ 0 & \text{if } \sum_{j:(j,i) \in A} y_{jiw} - \sum_{j:(i,j) \in A} y_{ijw} \geq \xi_{iw}^s \end{cases}, \quad \forall s \in \Omega, i \in D_w, w \in W$$

Big-M reformulation of chance constraints III

Chance constraint is equivalent to the following set of MIP constraints:

$$- \sum_{j:(i,j) \in A} y_{ijw} + \sum_{j:(j,i) \in A} y_{jiw} - \xi_{iw}^s + \mathbf{M}_{iw} z_{iw}^s \geq 0 \quad \forall s \in \Omega, i \in D_w, w \in W \quad (9)$$

$$\sum_{s \in \Omega} p^s z_{iw}^s \leq \epsilon_{iw} \quad \forall i \in D_w, w \in W \quad (10)$$

$$\mathbf{z}_{iw} \in \{0, 1\}^{|\Omega|} \quad \forall i \in D_w, w \in W \quad (11)$$

where \mathbf{M} is an arbitrarily large number.

Polynomial-time algorithm for PNDP-cont-nc I

- An alternative method that does not require the use of binary variables
- Takes advantage of single-line chance constraints
- If

$$\sum_{j:(j,i) \in A} y_{jiw} - \sum_{j:(i,j) \in A} y_{ijw} \geq \xi_{iw}^s$$

for some realization ξ_{iw}^s , then

$$\sum_{j:(j,i) \in A} y_{jiw} - \sum_{j:(i,j) \in A} y_{ijw} \geq \xi_{iw}^{s'}$$

for any realization satisfying $\xi_{iw}^{s'} < \xi_{iw}^s$.

Polynomial-time algorithm for PNDP-cont-nc II

ALGO1:

for all $w \in W, i \in D_w$

- (i) Sort ξ_{iw}^s in ascending order and relabel the scenarios based on this order
- (ii) Identify $s' \in \{1, \dots, |\Omega_{iw}|\}$ such that

$$\sum_{k=s}^{|\Omega_{iw}|} p^k > \epsilon_{iw} \geq \sum_{k=s'}^{|\Omega_{iw}|} p^k$$

- (iii) Replace the $(i, w)^{\text{th}}$ chance constraint with

$$\sum_{j:(j,i) \in A} y_{jiw} - \sum_{j:(i,j) \in A} y_{ijw} \geq \xi_{iw}^{s'} \quad (12)$$

end for

Solve PNDP-cont-nc as

$$\min_{\mathbf{x}, \mathbf{y}} \left\{ \sum_{(i,j) \in A} c_{ij} x_{ij} + \sum_{w \in W} \sum_{(i,j) \in A} a_{ijw} y_{ijw} : \text{subject to (1)-(4); (12)} \forall w \in W, i \in D_w \right\}$$

Polynomial-time algorithm for PNDP-cont-nc III

- Similar approaches can be used to develop polynomial-time algorithms for special cases of PNDP-cont-n/c
- PNDP-cont-n with each node having demand for no more than 1 type of commodity \Rightarrow single-line chance constraint
- PNDP-cont-c with each commodity having no more than 1 demand node \Rightarrow single-line chance constraint

Results for randomly generated networks I

- Compare computational times and optimal objective values for
 - PNDP-cont-joint
 - PNDP-cont-nc with homogenous (“-ho”) risk parameters
 - PNDP-cont-nc with heterogenous (“-he”) risk parameters

Results for randomly generated networks II

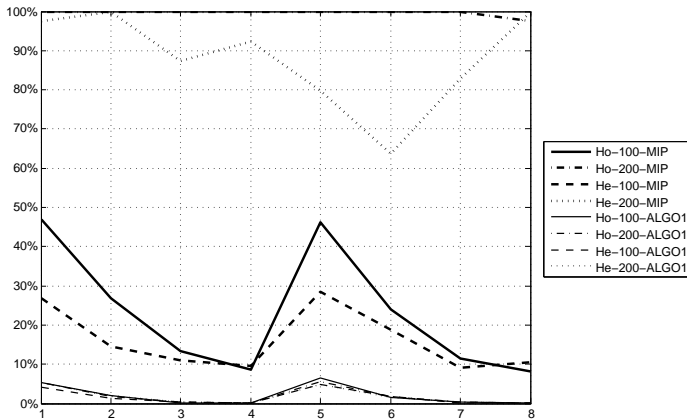


Figure : Percentage comparison of CPU time taken by ALGO1 and the MIP approach for PNDP-cont-nc instances (100% is the largest CPU time)

Results for randomly generated networks III

Summary of observations:

- Optimal objective values decrease as ϵ increases
- PNDP-cont-nc is less sensitive to changes in ϵ than PNDP-cont-joint
- ALGO1 is much more efficient than the MIP approach
- For MIP models, CPU time increases dramatically as ϵ is increased and as $|\Omega|$ is increased
- For ALGO1, CPU time increases is mostly unaffected by changes in ϵ and $|\Omega|$, and the homogeneity of risk parameters

Results for real life network I

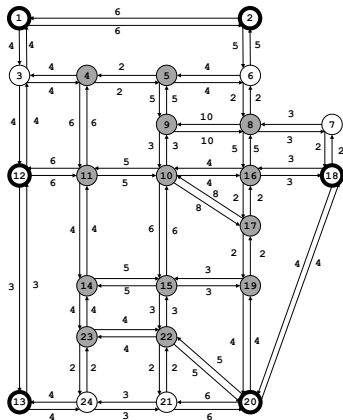


Figure : Sioux Falls road network

Results for real life network II

- High inflow instance
- Higher mean demands for nodes closer to node 10 (center node)
- Compare sensitivity of optimal objective values to ϵ and v
 - PNDP-cont-joint
 - PNDP-cont-nc
 - SNDP-cont-wp

Results for real life network III

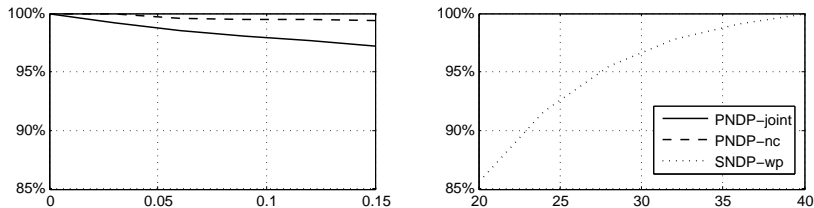


Figure : Percentage comparison of optimal objective values for PNDP-joint, PNDP-nc and SNDP-cont-wp

Results for real life network IV

Summary of observations:

- Optimal values of PNDP-joint and PNDP-nc have a fairly linear relationship with ϵ
- Optimal values of SNDP-cont-wp are concave w.r.t. v (dominant term changes from real cost to penalty cost)
 - Without first experimenting with several values of v , a suitable value for v may not be known
 - PNDP models mitigate ambiguity in solution reliability

Conclusions and future research

Conclusions:

- Developed MIP formulations for PNDP models
- Developed polynomial-time algorithms for PNDP-cont-nc and special cases of PNDP-cont-n/c models that are far more efficient than MIP formulations
- Benchmarked PNDP models against SNDP to find that PNDP models are far less sensitive to small changes in parameters

Future research:

- Risk parameters as variables, to seek an optimal combination of risk versus cost
- Special network topologies that may provide more effective algorithms

Thank you!