

9/12/22

Agenda: 2.2 exc.

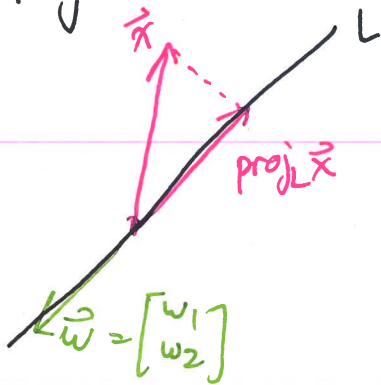
2.3 matrix mult.

Last time: • stretch by k_1 in the x-direction and ~~by~~

by k_2 in the y-direction: $\begin{bmatrix} k_1 & 0 \\ 0 & k_2 \end{bmatrix}$

• Rotate by θ : $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$

• Projection onto a line L : $\text{proj}_L(\vec{x}) = \frac{\vec{w} \cdot \vec{x}}{\vec{w} \cdot \vec{w}} \vec{w}$ for any vector \vec{w} parallel to L



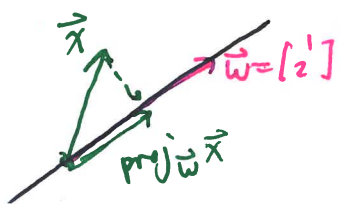
Matrix: $\frac{1}{\vec{w} \cdot \vec{w}} \begin{bmatrix} w_1 \vec{w} & w_2 \vec{w} \end{bmatrix}$

$$= \frac{1}{\vec{w} \cdot \vec{w}} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} \begin{bmatrix} w_1 & w_2 \end{bmatrix} = \frac{1}{\vec{w}^T \vec{w}} (\vec{w} \vec{w}^T)$$

$$\text{proj}_L(\vec{x}) = \frac{1}{\vec{w}^T \vec{w}} (\vec{w} \vec{w}^T) \vec{x}$$

This formula holds in 3D, 4D, etc.

exc 2.2 #30: find a 2×2 matrix A s.t. $A\vec{x}$ is parallel to $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ for all \vec{x}



A one answer is to take A to be the matrix for proj_w

$$\leadsto A = \frac{1}{\vec{w} \cdot \vec{w}} \begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \frac{1}{\vec{w}^T \vec{w}} \vec{w} \vec{w}^T$$

$$\vec{w} \cdot \vec{w} = \vec{w}^T \vec{w}$$

\uparrow dot product \uparrow matrix mult.

$$\vec{w}^T \cdot \vec{w} \text{ weird.}$$

$$\begin{aligned}
 &= \frac{1}{1 \cdot 1 + 2 \cdot 2} \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} \\
 &= \frac{1}{5} \begin{bmatrix} 1 \cdot 1 & 2 \cdot 2 \\ 2 \cdot 1 & 2 \cdot 2 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \\
 &= \begin{bmatrix} 1/5 & 2/5 \\ 2/5 & 4/5 \end{bmatrix}
 \end{aligned}$$

Another answer = We want $A\vec{x} = (\text{some constant}) \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

for all $\vec{x} \in \mathbb{R}^2$

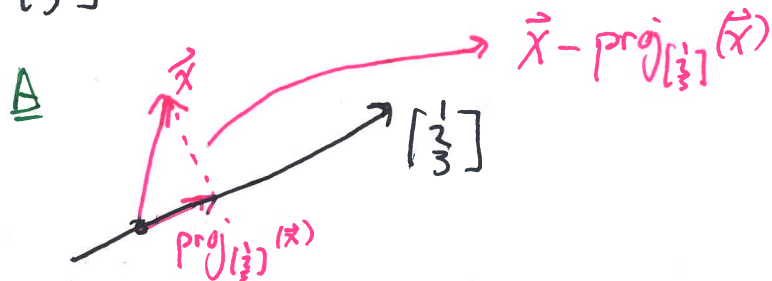
$$A = \left[67 \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad 22.1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right] = \begin{bmatrix} 67 & 22.1 \\ 134 & 44.2 \end{bmatrix}$$

$$\text{Then } A \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1 \begin{bmatrix} 67 \\ 134 \end{bmatrix} + x_2 \begin{bmatrix} 22.1 \\ 44.2 \end{bmatrix} = x_1 \cdot 67 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + x_2 \cdot 22.1 \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \underbrace{(67x_1 + 22.1x_2)}_{\text{some const.}} \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

In general, $A = \left[c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad c_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right]$ works.

#3] Find a 3×3 matrix A s.t. $A\vec{x}$ is perpendicular to $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ for all $\vec{x} \in \mathbb{R}^3$



Matrix for $\text{proj}_{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}}$:

$$\begin{aligned}
 M_L &= \frac{1}{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \end{bmatrix} \\
 &= \frac{1}{1 \cdot 1 + 2 \cdot 2 + 3 \cdot 3} \begin{bmatrix} 1 \cdot 1 & 1 \cdot 2 & 1 \cdot 3 \\ 2 \cdot 1 & 2 \cdot 2 & 2 \cdot 3 \\ 3 \cdot 1 & 3 \cdot 2 & 3 \cdot 3 \end{bmatrix}
 \end{aligned}$$

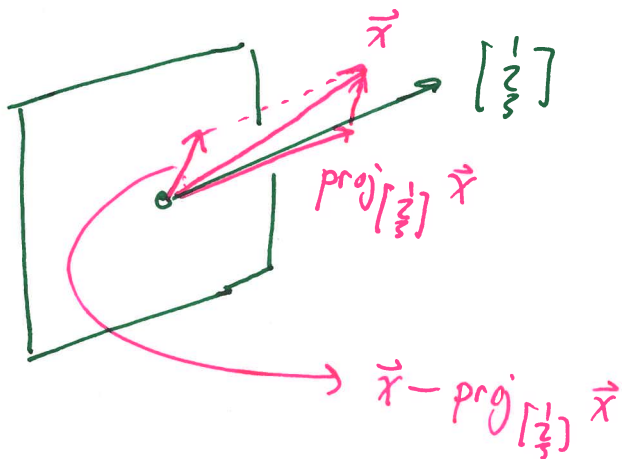
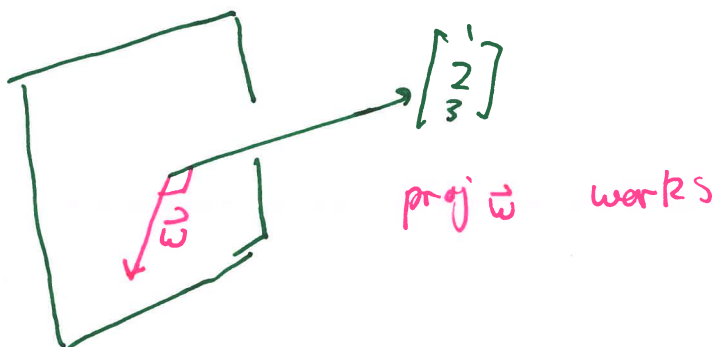
Answer: $\text{Id}_3 - M_L$, because $(\text{Id}_3 - M_L) \vec{x} = \text{Id} \vec{x} - M_L \vec{x} = \vec{x} - \text{proj}_{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}} \vec{x}$

$A^2 = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$ is perpendicular to $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$:

$$\begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = -1 \cdot 1 + -1 \cdot 2 + 1 \cdot 3 = 0$$

So the matrix for $\text{proj}_{\begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}}$ works.

$\begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$ is also perpendicular to $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$.



§2.3

let $T_1: \mathbb{R}^a \rightarrow \mathbb{R}^b$, $T_2: \mathbb{R}^b \rightarrow \mathbb{R}^c$ be linear.

The function sending any vector $\vec{v} \in \mathbb{R}^a$ to $T_2(T_1(\vec{v}))$ is a linear function, from \mathbb{R}^a to \mathbb{R}^c .

Notation: $(T_2 \circ T_1)(\vec{v}) = T_2(T_1(\vec{v}))$

So $T_2 \circ T_1: \mathbb{R}^a \rightarrow \mathbb{R}^c$ is linear.

What is its matrix?

Let M_1 be the matrix of T_1 , M_2 be the matrix of T_2 .

Then $(T_2 \circ T_1)(\vec{v}) = T_2(T_1(\vec{v})) = T_2(M_1 \vec{v}) = M_2 \cdot (M_1 \vec{v}) = (M_2 \cdot M_1) \vec{v}$

Composition of linear functions \iff Multiplication of matrices