

Finish 3.3, start 3.4

Exam: Oct 10

Recap: 3.2: A Subspace of \mathbb{R}^n is the span of some vectors.

• $\{\vec{v}_1, \dots, \vec{v}_r\}$ is "linearly independent" if no vector is contained in the span of the others.

$\Rightarrow \text{Span}\{\vec{v}_1, \dots, \vec{v}_r\} \neq \text{Span}\{\vec{v}_1, \dots, \vec{v}_r\}$

See "Summary 3.2.9"

• $\{\vec{v}_1, \dots, \vec{v}_r\}$ is lin indep $\iff \ker[\vec{v}_1, \dots, \vec{v}_r] = \{0\}$

\iff if $c_1\vec{v}_1 + \dots + c_r\vec{v}_r = 0$, then $c_1, \dots, c_r = 0$

Def (Basis) Let $U \subseteq \mathbb{R}^n$ be a subspace. Then a set of vectors $\vec{w}_1, \dots, \vec{w}_r \in U$ is called a basis of U if: $\vec{w}_1, \dots, \vec{w}_r$ are lin. indep. and $\text{span}\{\vec{w}_1, \dots, \vec{w}_r\} = U$

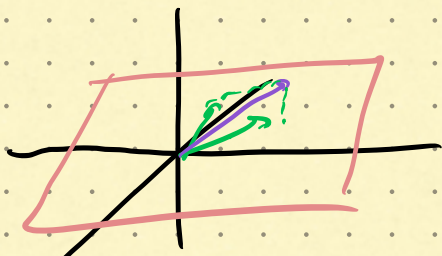
3.3 Dimension

Let $U \subseteq \mathbb{R}^n$ be a subspace.

(Thm 3.3.4) Deep fact: Max size of a lin. indep. set of vectors in $U =$ min size of any set of vectors which spans U .
(part of it)

This # is called the dimension of U .

eg. Consider a plane in \mathbb{R}^3 :



• you can't span the plane w/ fewer than 2 vectors,

• any set of more than 2 vectors in this

plane will be lin. dependent!

So this plane is a 2-dimensional subspace of \mathbb{R}^3 .

If $V \subseteq \mathbb{R}^n$ is a subspace, then any basis for V must have exactly $\dim(V)$ elements.

(e.g. any basis of that plane must consist of 2 vectors)

Exercise: let $A = \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 2 & 0 \\ 1 & 0 & 2 & 0 \\ 0 & 1 & 2 & 0 \end{bmatrix}$

find a basis for $\text{im}(A)$ and a basis for $\text{ker}(A)$.

Solve using row reduction.

$\text{ker}(A) = ?$ Solve $A\vec{x} = \vec{0} \rightsquigarrow \begin{bmatrix} 1 & 0 & 2 & 0 & | & 0 \\ 0 & 1 & 2 & 0 & | & 0 \\ 1 & 0 & 2 & 0 & | & 0 \\ 0 & 1 & 2 & 0 & | & 0 \end{bmatrix}$

RREF $\begin{bmatrix} 1 & 0 & 2 & 0 & | & 0 \\ 0 & 1 & 2 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix} \rightsquigarrow \begin{cases} x_1 + 2x_3 = 0 \\ x_2 + 2x_3 = 0 \end{cases}$

$\Rightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -2x_3 \\ -2x_3 \\ x_3 \\ x_4 \end{bmatrix} = x_3 \begin{bmatrix} -2 \\ -2 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$

$\Rightarrow \text{ker}(A)$ is spanned by $\begin{bmatrix} -2 \\ -2 \\ 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$. Also, ~~can be~~

these two vectors are lin. indep.

$\Rightarrow \begin{bmatrix} -2 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$ is a basis for $\text{ker}(A)$.

so these are a basis for $\text{im}(A)$.

pivot cols.

↓ ↓

$$A = \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 2 & 0 \\ 1 & 0 & 2 & 0 \\ 0 & 1 & 2 & 0 \end{bmatrix}$$

$$\text{RREF}(A) = \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$\text{im}(A)$ is spanned by $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$

But, this not lin. indep! So we need to throw out some vectors to get a basis for $\text{im}(A)$,

Here: $2 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 2 \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2 \\ 2 \end{bmatrix}$, so $\begin{bmatrix} 2 \\ 2 \\ 2 \\ 2 \end{bmatrix}$ is redundant,

$$0 \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

We're left with $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \right\}$, and these are lin. indep!

In general, look at the pivot columns of A .

3.4

In Exercises 1 through 18, determine whether the vector \vec{x} is in the span V of the vectors $\vec{v}_1, \dots, \vec{v}_m$ (proceed "by inspection" if possible, and use the reduced row-echelon form if necessary). If \vec{x} is in V , find the coordinates of \vec{x} with respect to the basis $\mathcal{B} = (\vec{v}_1, \dots, \vec{v}_m)$ of V , and write the coordinate vector $[\vec{x}]_{\mathcal{B}}$.

1. $\vec{x} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}; \vec{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

2. $\vec{x} = \begin{bmatrix} 23 \\ 29 \end{bmatrix}; \vec{v}_1 = \begin{bmatrix} 46 \\ 58 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 61 \\ 67 \end{bmatrix}$

3. $\vec{x} = \begin{bmatrix} 31 \\ 37 \end{bmatrix}; \vec{v}_1 = \begin{bmatrix} 23 \\ 29 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 31 \\ 37 \end{bmatrix}$

→ 4. $\vec{x} = \begin{bmatrix} 3 \\ -4 \end{bmatrix}; \vec{v}_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

5. $\vec{x} = \begin{bmatrix} 7 \\ 16 \end{bmatrix}; \vec{v}_1 = \begin{bmatrix} 2 \\ 5 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 5 \\ 12 \end{bmatrix}$

Translation:



• Does the system

$$\begin{bmatrix} \vec{v}_1 & \vec{v}_2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \vec{x}$$

\uparrow unknowns.

have a solution $\begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$?

• If so, what is the solution?

eg #4 $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 3 \\ -4 \end{bmatrix} \rightarrow c_2 = 3, c_1 = -4$

$\begin{bmatrix} c_2 \\ c_1 \end{bmatrix} \rightarrow [\vec{x}]_{\mathcal{B}} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} -4 \\ 3 \end{bmatrix}$

3.3

$$A = \begin{bmatrix} 1 & -2 & 0 & -1 & 0 \\ 0 & 0 & 1 & 5 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$v_1 \quad v_2 \quad v_3 \quad v_4 \quad v_5$

find bases for $\text{im}(A)$, $\text{ker}(A)$ "by inspection"

Basis for $\text{im}(A)$? The vectors v_1, \dots, v_5 span $\text{im}(A)$,

v_2 and v_4 look redundant:

$$\begin{cases} v_2 = -2v_1 \\ v_4 = -v_1 + 5v_3 \end{cases}$$

Another argument: $\text{span}(v_1, v_3, v_5) = \mathbb{R}^3$, so v_1, v_3, v_5 span $\text{im}(A)$.

Also, v_1, v_3, v_5 are lin. indep, so this is a basis for $\text{im}(A)$.

$\text{ker}(A) = ?$ $2v_1 + v_2 = 0 \rightarrow \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \in \text{ker}(A),$

$v_1 + v_4 - 5v_3 = 0 \rightarrow \begin{bmatrix} 1 \\ 0 \\ -5 \\ 0 \\ 0 \end{bmatrix} \in \text{ker}(A),$

and they're lin. indep.

Are we done? Rank-nullity thm:

$$\dim(\text{ker}(A)) = \underbrace{\# \text{cols of } A}_5 - \underbrace{\dim(\text{im}(A))}_3$$

$= 2.$

So we already found out 2 basis vectors.